**Current Research Progress**

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1. Previous reproduction summary

(1) Simulation environment

\* Hardware Specifications \* Software Versions

– CPU. Intel i7-8700 – python 3.7.13

– GPU. Geforce RTX 2060 – torch 1.12.0

– RAM. DDR5-3600 32GB – torchvision 0.13.0

(2) Simulation results

- Inference speed = 8\*16 / 3 = 128 / 3 = 42.66 fps

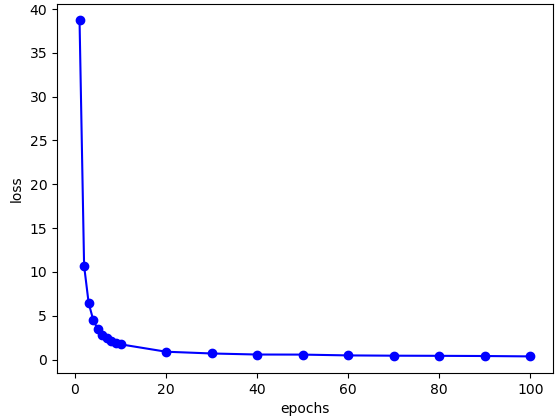
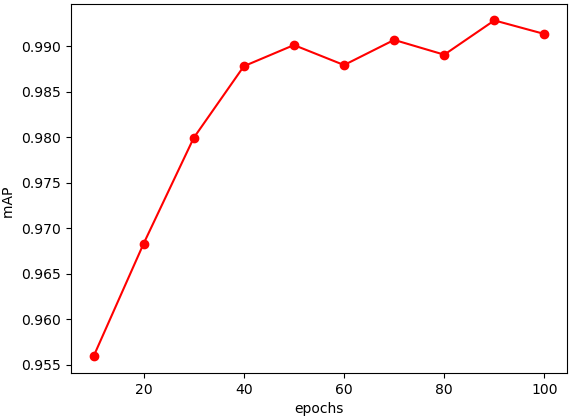
On Test loader:

100%|██████████████████████████████████████████| 7/7 [00:03<00:00, 1.81it/s]

Class accuracy is: 100.000000%

No obj accuracy is: 73.054192%

Obj accuracy is: 100.000000%

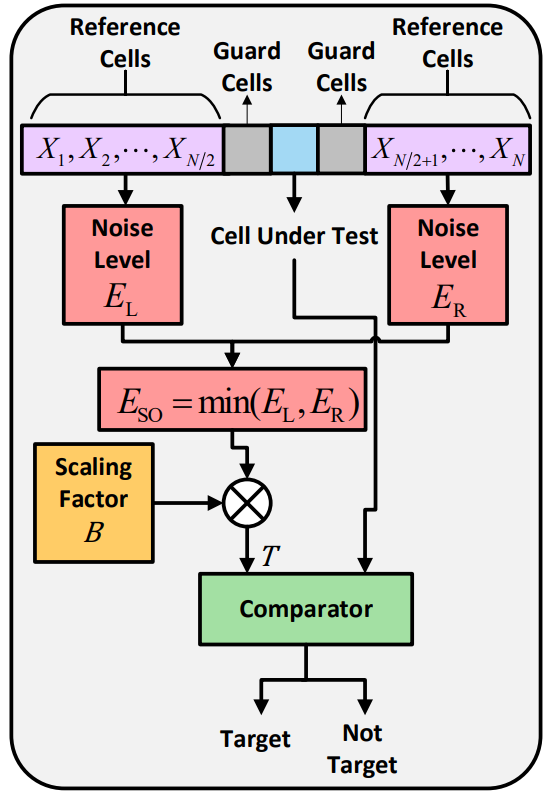
- Training loss - mAP (mean Average Precision)

2. CFAR related works

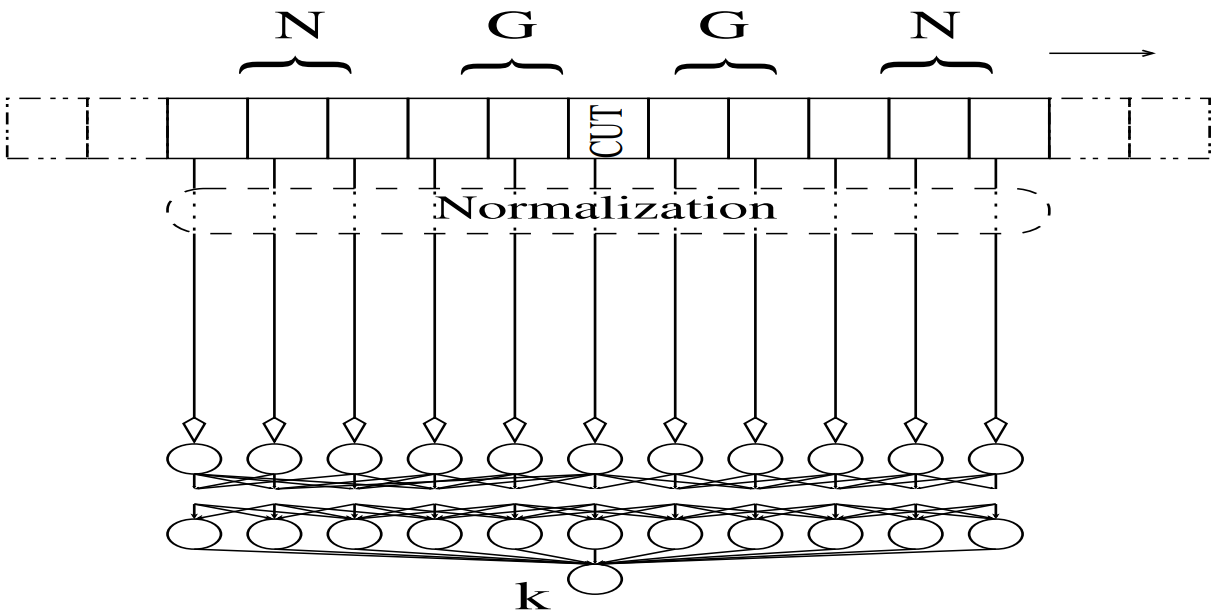
(1) J. Akhtar, "Training of Neural Network Target Detectors Mentored by SO-CFAR," *2020 28th European Signal Processing Conference (EUSIPCO)*, 2021, pp. 1522-1526

(2) J. Akhtar and K. E. Olsen, "GO-CFAR Trained Neural Network Target Detectors," *2019 IEEE Radar Conference (RadarConf)*, 2019, pp. 1-5

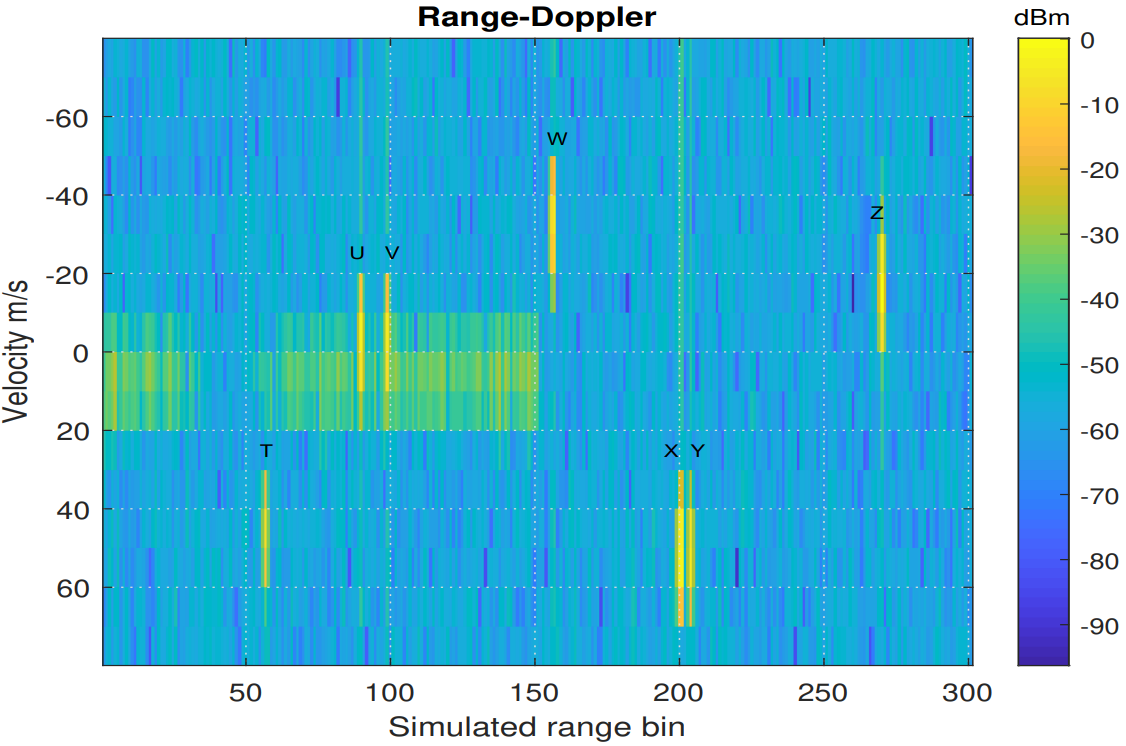
(3) J. Akhtar and K. E. Olsen, "A Neural Network Target Detector with Partial CA-CFAR Supervised Training," *2018 International Conference on Radar (RADAR)*, 2018, pp. 1-6



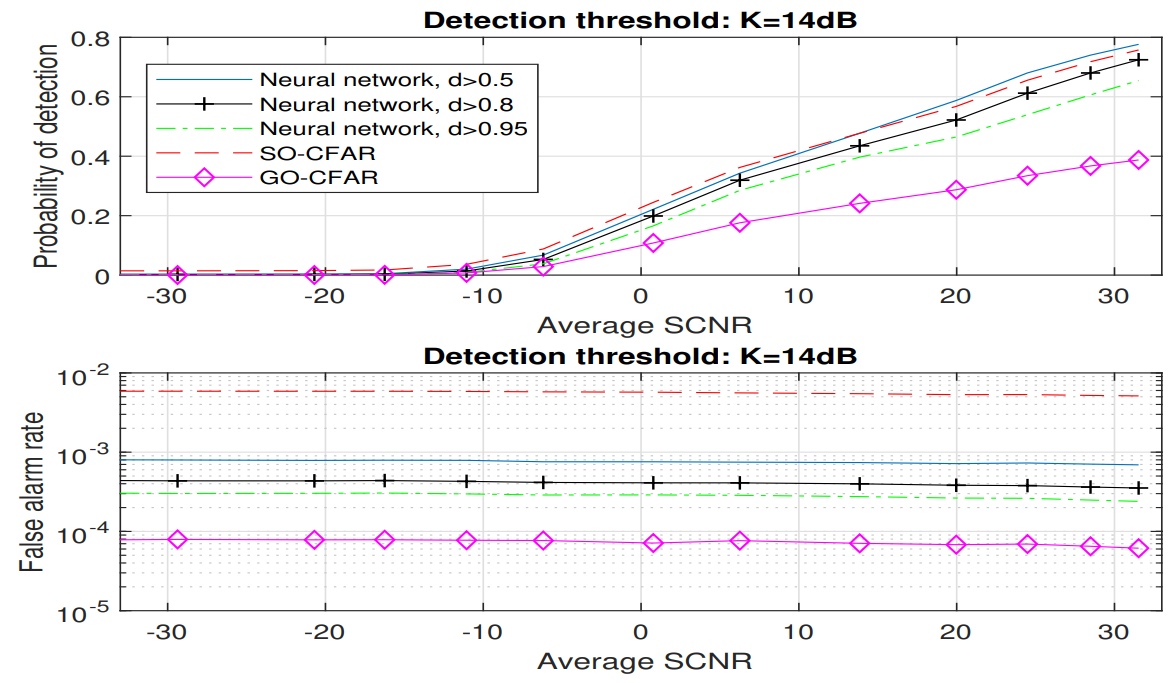
- Neural network detector



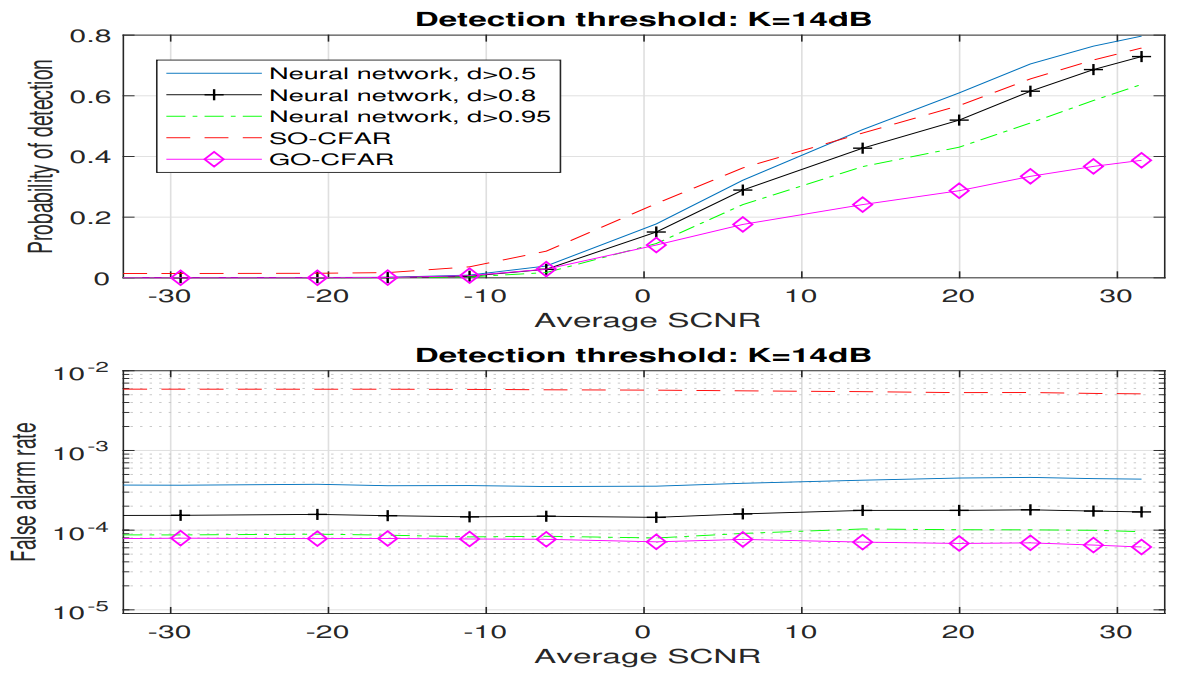
- Simulated range-Doppler map



- showing that adding an additional NN classifier at the end can reduce false alarm rate performance.



- showing that taken account more reference cells, say 2 cells above CUT and 2 cells below CUT, resulted in better false alarm rate performance.

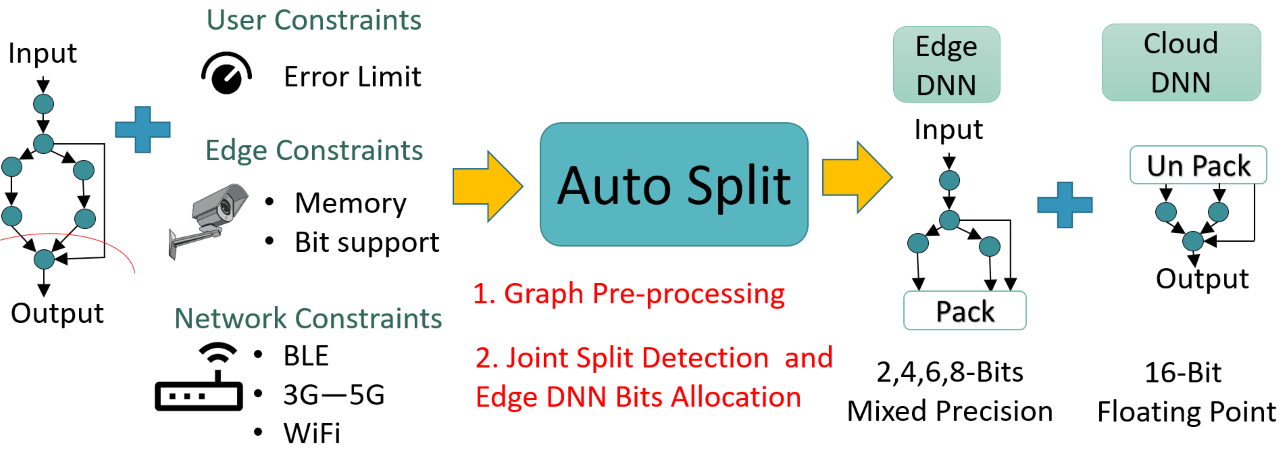


3. YOLO related works

(1) Amin Banitalebi-Dehkordi, Naveen Vedula, Jian Pei, Fei Xia, Lanjun Wang, and Yong Zhang. 2021. “Auto-Split: A General Framework of Collaborative Edge-Cloud AI[[1]](#footnote-1).” I*n Proceedings of the 27th ACM SIGKDD Conference on Knowledge Discovery & Data Mining (KDD '21)*.

- Overview

Auto split engine takes a DNN as input and finds the best split point to execute the initial DNN on the edge device and the later DNN on the cloud device to minimize end-to-end latency.



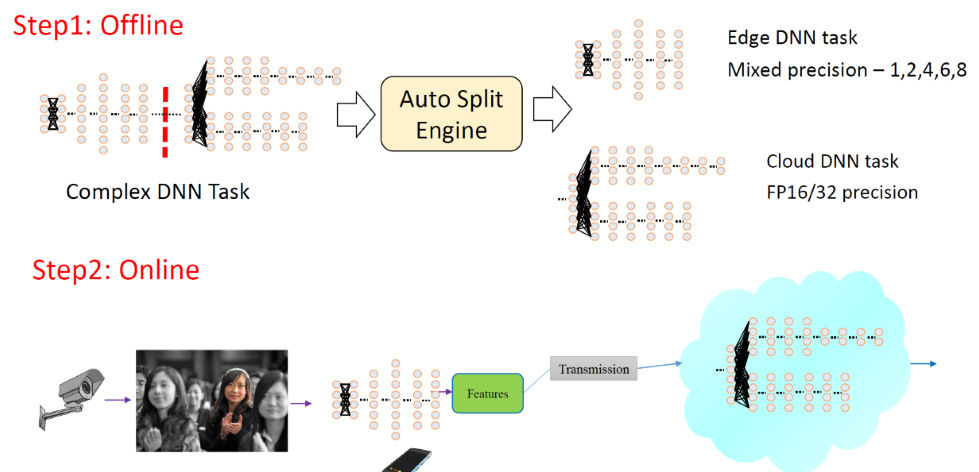
- Quantization Support

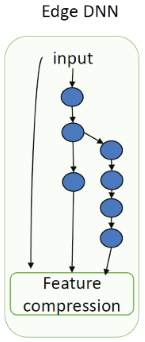
For edge device, it also finds quantization statistics, and bit-width per layer to apply various post training quantization techniques such as Loss Aware Post-training Quantization (LAPQ)[[2]](#footnote-2), ACIQ: Analytical Clipping for Integer Quantization of neural networks (ACIQ)[[3]](#footnote-3).

- Reduced Transmission Cost

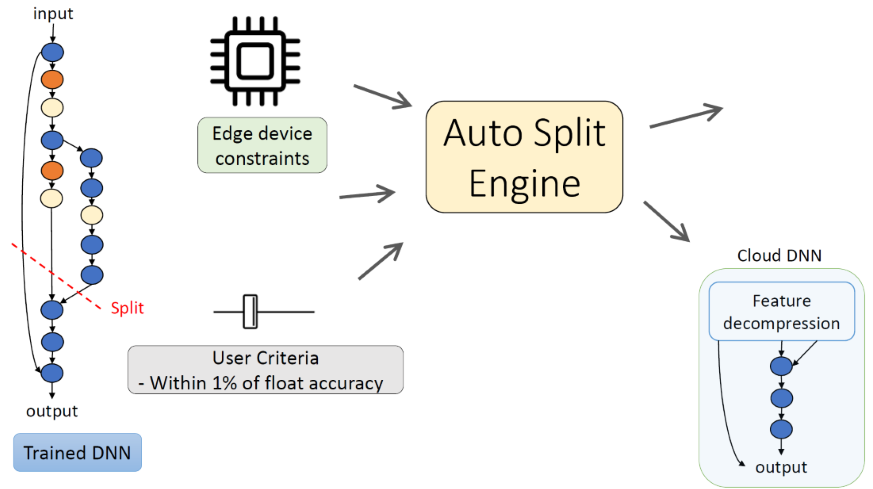
At the split point, the auto-split engine parses the DNN graph and collects the features to be transmitted to the cloud device at lower precision reducing the total transmission cost.

- Cloud device executes in floating point precision[[4]](#footnote-4)





- Auto split engine



- Auto-Split Solution

For Auto-Split solution, the Darknet based Yolov3 object detection is split into two parts, the edge DNN and cloud DNN.

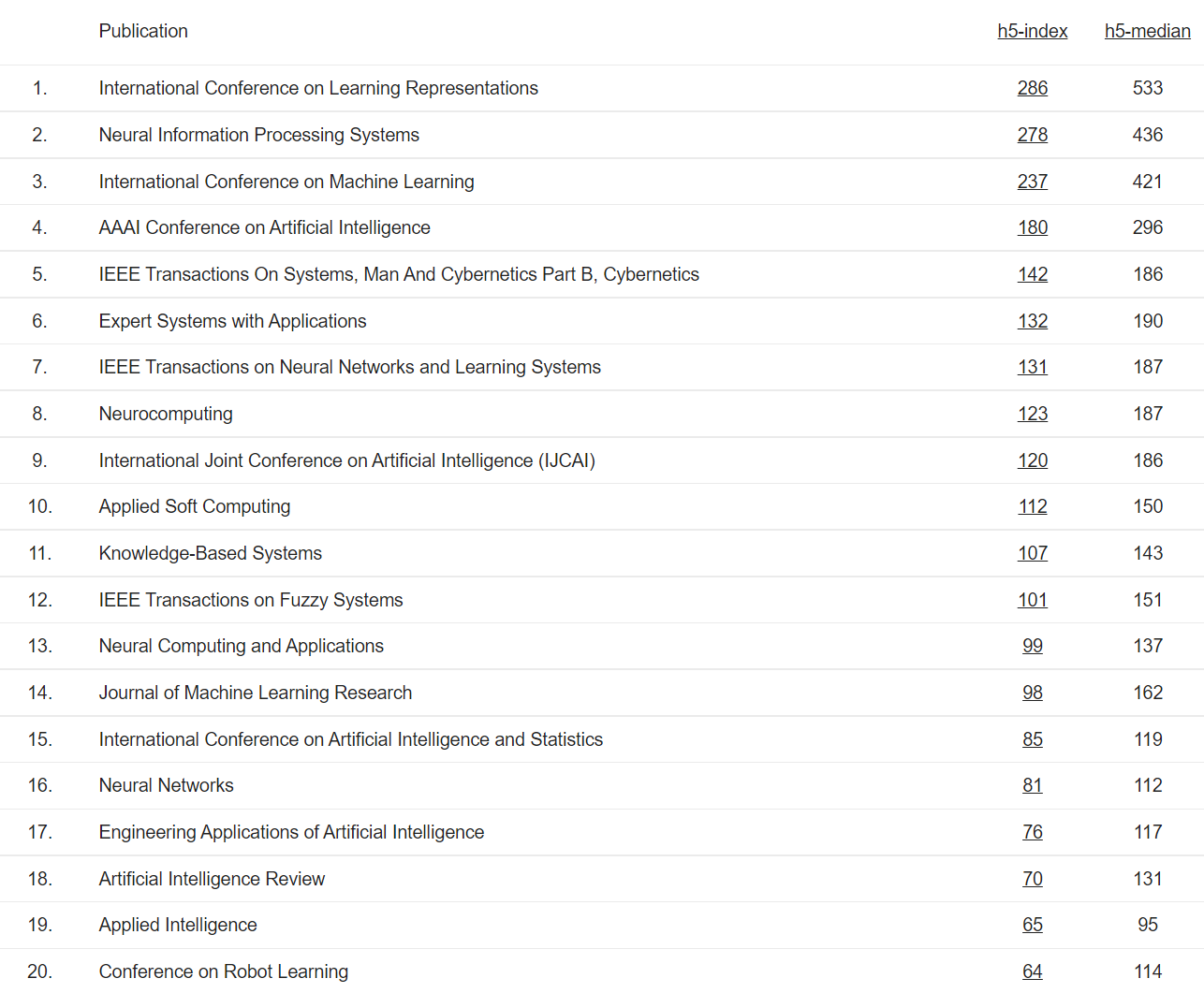
The split point was suggested by the Auto-split algorithm. They manually partition the YOLOv3 into edge DNN and cloud DNN.

For the demo, the video executes each frame on the edge DNN and transmits activations to an IP address, which is then received by the cloud DNN on the GPU of that IP address.

In their example, they use the same device to transmit the data.

Appendix

- Artificial Intelligence[[5]](#footnote-5)



1. Amin Banitalebi-Dehkordi, Naveen Vedula, Jian Pei, Fei Xia, Lanjun Wang, and Yong Zhang. 2021. Auto-Split: A General Framework of Collaborative Edge-Cloud AI. *In Proceedings of the 27th ACM SIGKDD Conference on Knowledge Discovery & Data Mining (KDD '21)*. <https://dl.acm.org/doi/abs/10.1145/3447548.3467078> [↑](#footnote-ref-1)
2. Ron Banner, Yury Nahshan, Elad Hoffer, Daniel Soudry. ACIQ: Analytical Clipping for Integer Quantization of neural networks. *ICLR 2019 Conference*. <https://github.com/submission2019/cnn-quantization> [↑](#footnote-ref-2)
3. Nahshan, Y., Chmiel, B., Baskin, C. et al. Loss aware post-training quantization. *Mach Learn 110*, 3245–3262 (2021). <https://github.com/ynahshan/nn-quantization-pytorch/tree/master/lapq> [↑](#footnote-ref-3)
4. Paulius Micikevicius, Sharan Narang, Jonah Alben, Gregory Diamos, Erich Elsen, David Garcia, Boris Ginsburg, Michael Houston, Oleksii Kuchaiev, Ganesh Venkatesh, Hao Wu. Mixed Precision Training. *ICLR 2018 Conference*. <https://arxiv.org/abs/1710.03740> [↑](#footnote-ref-4)
5. https://scholar.google.es/citations?view\_op=top\_venues&hl=en&vq=eng\_artificialintelligence [↑](#footnote-ref-5)